Cognitive Systems
Practical Exercises – Reconfiguration of workspace

Prof. Dr.-Ing. habil. Alois Knoll
Alexander Perzylo, Nikhil Somani, Ahmed Ghazi, Hendrik Walzel
Robotics and Embedded Systems (Informatik VI)
TUM
Outline

• Remove all existing ROS packages
• SVN checkout ROS packages
• Build the packages
• Run the required ROS nodes
Remove all existing ROS packages

- Open a new Terminal
- Change to ~/catkin_cogsys-ros/src directory
- Remove all packages from src-folder
SVN checkout ROS packages

• Checkout ROS packages from new SVN repository

• (See cogsyst_howto_v3.txt from lecture's website for copy & paste approach)
Build the packages

- Change directory to ~/catkin_cogsys-ros/
- Invoke catkin_make
Run the required ROS nodes

• If everything was built successfully, execute the following commands in the given sequence

• Download ROS camera bag file (if you haven't done so yet)

• (See cogsys_howto_v3.txt from lecture's website for copy & paste approach)
Run the required ROS nodes

- Open 8 Terminal windows and execute the following commands in the given sequence:
  - roscore
  - cogsys_visualization
  - Robot controllers
  - camera_dummy
  - Play ROS bag file
  - object_detector
  - world_model
  - demo_cogsys_viz_cpp