GUI Development for Human-Robot Interaction

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Motivation
When humans and robots collaborate, humans need to have on the one hand sufficient information about the robotic system and its internal status and on the other hand a possibility to control and correct the robotic system.

Set-up
The work will take place in the CoTeSys demonstration scenario „the cognitive factory“ on the human-robot collaboration platform „JAHIR“.

Task
The modules that are already in use on the set-up (visualization, several input and output modules) should be used to create a GUI to control the system and to view its internal status.

Interested?
Just give me a call (289-25761) or write an email (lenz@in.tum.de) for further details.

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